

**CERTIFICATE NO FS/71/220/23/1190**

ZERTIFIKAT NR.:

**PAGE 1/2**

SEITE(N)

**LICENCE HOLDER**

GENEHMIGUNGSINHABER

Rokae (Shandong) Robotics Technology Co., Ltd.  
No. 888 Huarun Rd., Zoucheng, Jining, Shandong, China

**MANUFACTURING PLANT**

FERTIGUNGSSTÄTTE

Rokae (Shandong) Robotics Technology Co., Ltd.  
No. 888 Huarun Rd., Zoucheng, Jining, Shandong, China

**PROJECT NO/-ID**

PROJEKT-NR/-ID

U2MS

**LICENSED TEST MARK**

GENEHMIGTES PRÜFZEICHEN



**Technical REPORT NO.**

TECHNISCHER BERICHT NR.

U2MS0001

**Tested according to**

Geprüft nach

ISO 13849-1:2015 / PL d, Category 3

**Certified product(s)**

Zertifizierte(s) Produkt(e)

Safety Control Module

**Model(s)**

Modell(e)

RSC\_MAIN

**Technical Data and Parameter**

Technische Daten und Parameter

The product fulfill the requirements of functional safety acc. to above standards in accordance with PL d. It is designed with a hardware architecture according to Category 3.

**Specific Requirements**

Spezifische Anforderungen

This certificate confirms the achievement of the requirements based on the following proofs:

- Proof of systematic safety integrity for defined phases of the life cycle
- Proof of the required safety-related parameters (failure rate, MTTF<sub>D</sub>, DC, CCF, CAT, PFH<sub>D</sub>)
- Proof of the techniques and measures according to ISO 13849-1
- Proofs that processes and methods are established at the manufacturer guaranteeing that unexceptionable processes in terms of risk analysis, design, production, validation, change management and quality management comply with the safety-related standard.

**Certification Body  
for Functional Safety  
SGS-TÜV Saar GmbH**

Zertifizierungsstelle für Funktionale Sicherheit

The test mark regulation is an integral part of this certificate.  
Die Prüf- und Zertifizierungsordnung ist integraler Bestandteil des Zertifikates.

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Munich, 2023-09-11

*Robert Sammer*

Robert Sammer

## APPENDIX

### Supplementary of Functional Safety Certificate

#### Summary of Safety Functions:

SF	Item & Description	PL Achieved	Response Time	MTTF <sub>D</sub> (years)	PFH <sub>D</sub>	Safe State
SF1	Safety application configuration with DI-LOGIC-DO	PL d with Cat. 3, DC ≥ 90%	30ms	582.23	4.29×10 <sup>-8</sup>	Switch off and high impedance.
SF2	Safety application configuration with FSOE-LOGIC-DO	PL d with Cat. 3, DC ≥ 90%	100ms	616.96	4.29×10 <sup>-8</sup>	Switch off and high impedance.
SF3	Safety application configuration with DI-LOGIC-FSOE	PL d with Cat. 3, DC ≥ 90%	100ms	765.77	4.29×10 <sup>-8</sup>	The RSC_MAIN Safety control module stop sending information or send error information to co-robot system via FSOE.
SF4	Safety application configuration with FSOE-LOGIC-FSOE	PL d with Cat. 3, DC ≥ 90%	100ms	827.01	4.29×10 <sup>-8</sup>	The RSC_MAIN Safety control module stop sending information or send error information to co-robot system via FSOE.
SF5	Safety application configuration with DI-LOGIC-DO-FSOE	PL d with Cat. 3, DC ≥ 90%	100ms	582.23	4.29×10 <sup>-8</sup>	Switch off and high impedance. The RSC_MAIN Safety control module stop sending information or send error information to co-robot system via FSOE.